



Curtin University

# Remote sensing

Fish, Cameras and Computers

August 19, 2014



What major changes will ocean sciences be experiencing in the next 3-5 years due to the continued technological innovation in remote sensing?

Fish ecologist with conservation management background

Remote sensing = close range (1-10m) stereo-video

# Challenges

1. The need for non destructive (fishery independent) data
2. The need to sample deeper (shelf and slope)
3. The pelagic

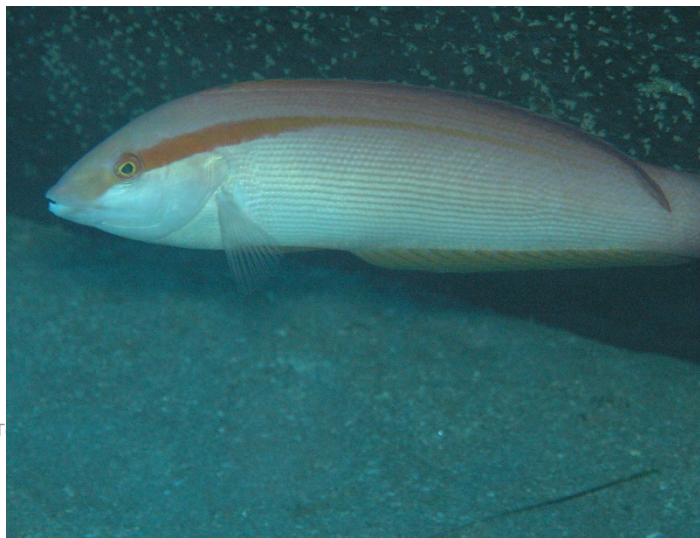
# Fisheries: What information do we want?

## Also marine benthos and plankton!

- Species identification
- Counts of abundance
- Length (biomass)
- Sex?



*Coris auricularis*



# Non destructive data

- Trawls, poisons, long-lines, hook and line, traps, nets  
+ Catch Fish -> Age, growth, sex, reproductive capacity
- Can't sample in some habitats, effects on habitat?
  - The effect of repeated sampling (Serial depletion)
  - Selectivity - > species biases (behavior)
  - Marine Protected Areas
  - Fine scale sampling within habitats
  - Need for fishery independent data particularly for EBFM and ESD

# Fishery Independent sampling

Can convert XYZ into:

Distance

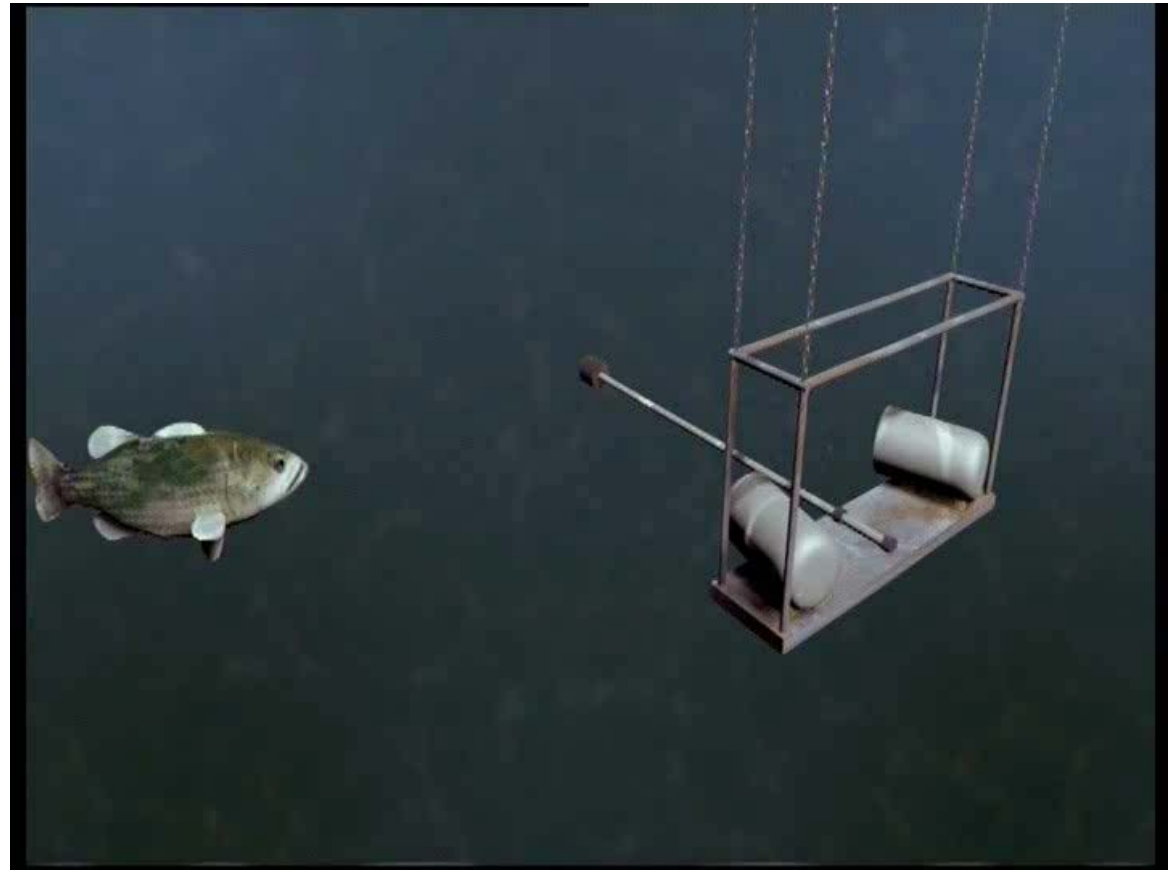
Angle (define sample unit)

Length

Biomass or volume

Swimming speed

Full high definition  
accuracy less 0.7% object  
length



Stereo-video

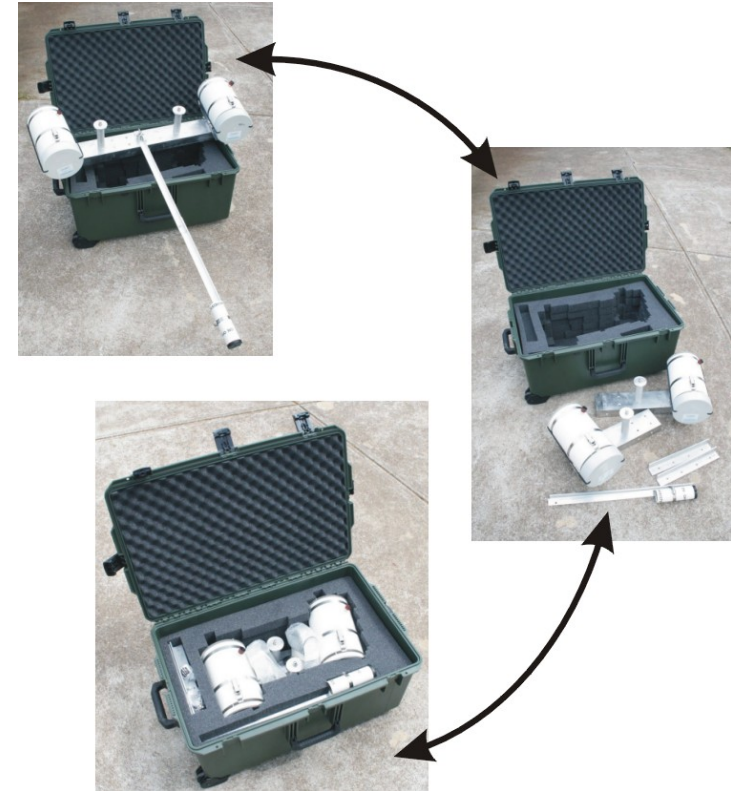
Harvey et al. 2010. Marine Technology Society  
Journal. 44(1): 75 – 85.



# Diver operated Stereo-video for UVC



- Neutrally buoyant, manoeuvrable
- Deployable from small boats
- Simple to use
- Removes inter-observer variability

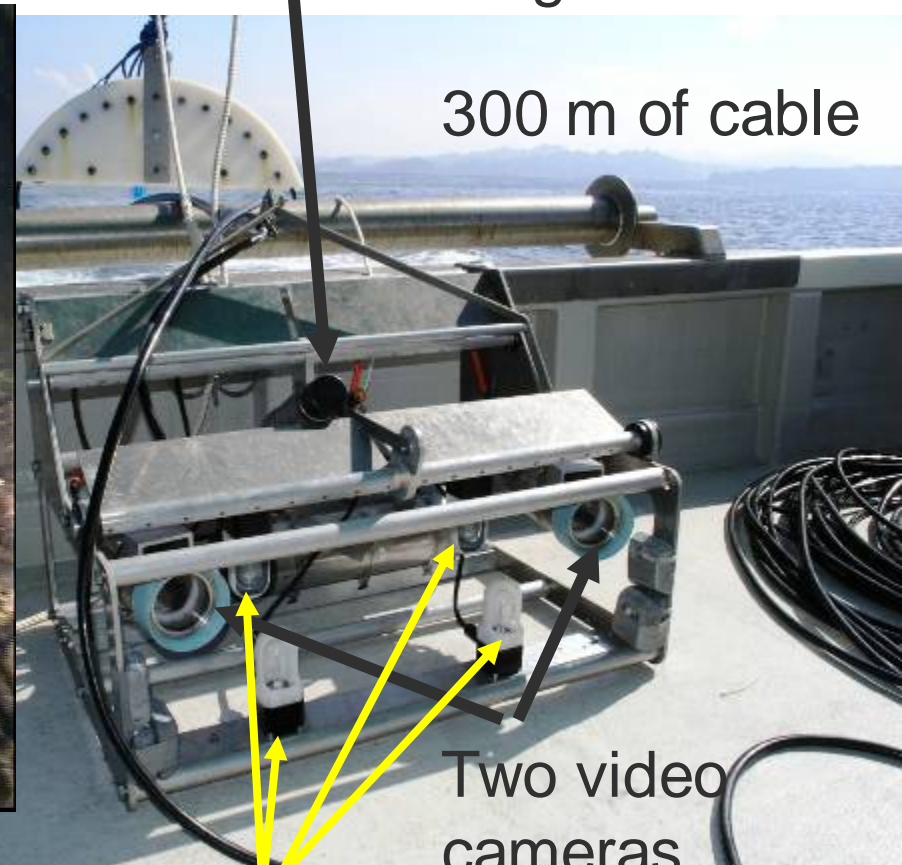


## Citizen Science

Harvey E, Shortis M (1995) Marine  
Technology Society Journal 29:10-22

# Drift /Towed/ drop stereo-video

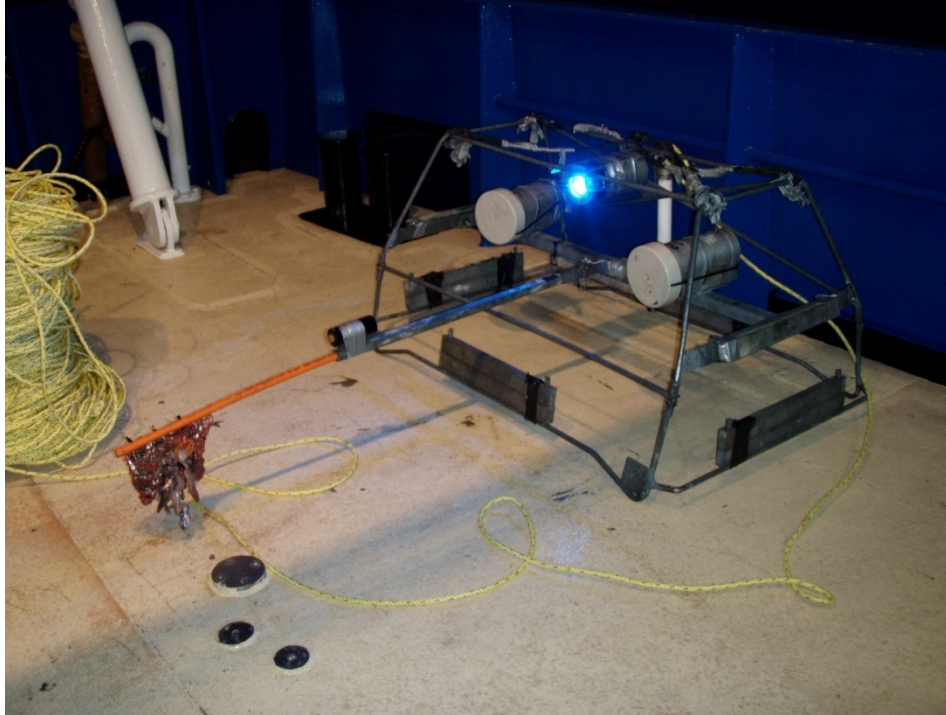
## Acoustic Positioning Beacon



McIlwain JL et al. Fisheries Oceanography (2011) 20:497-516  
Williams K, Rooper CN, Towler R (2010) Fishery Bulletin 108:352-362  
Rooper CN, Martin MH, Butler JL, Jones DT, Zimmermann M (2012) Fishery Bulletin 110:317-3  
Jones DT, et al (2012) Fishery Bulletin 110:332-343



# Baited remote underwater stereo-video (Stereo BRUVs)



Cost effective

Good statistical power

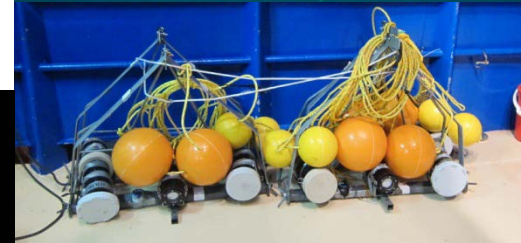
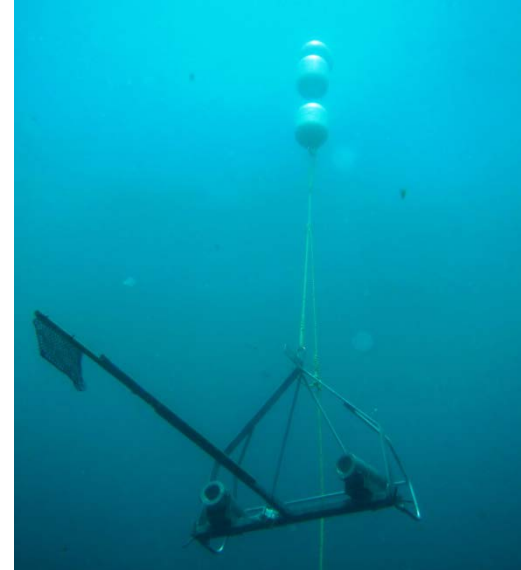
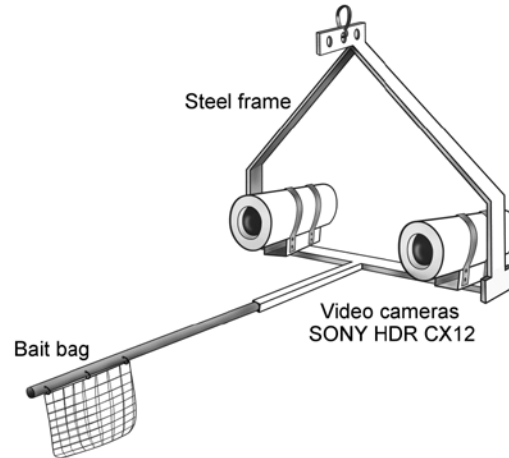
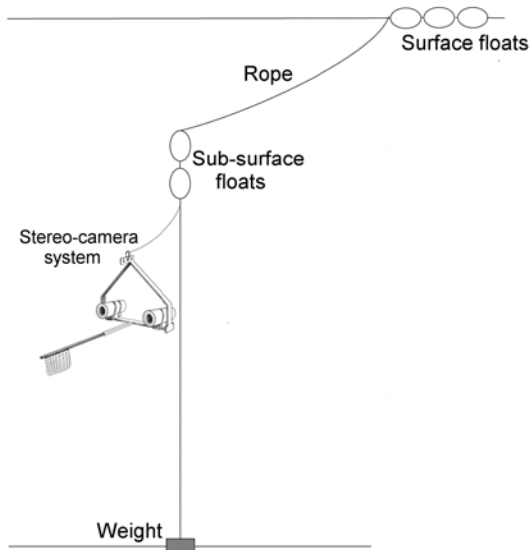
Watson et al. 2010. Marine Biology. 157(6): 1237-1250

Langlois et al 2010. Aquatic Biology. 9: 155 – 168

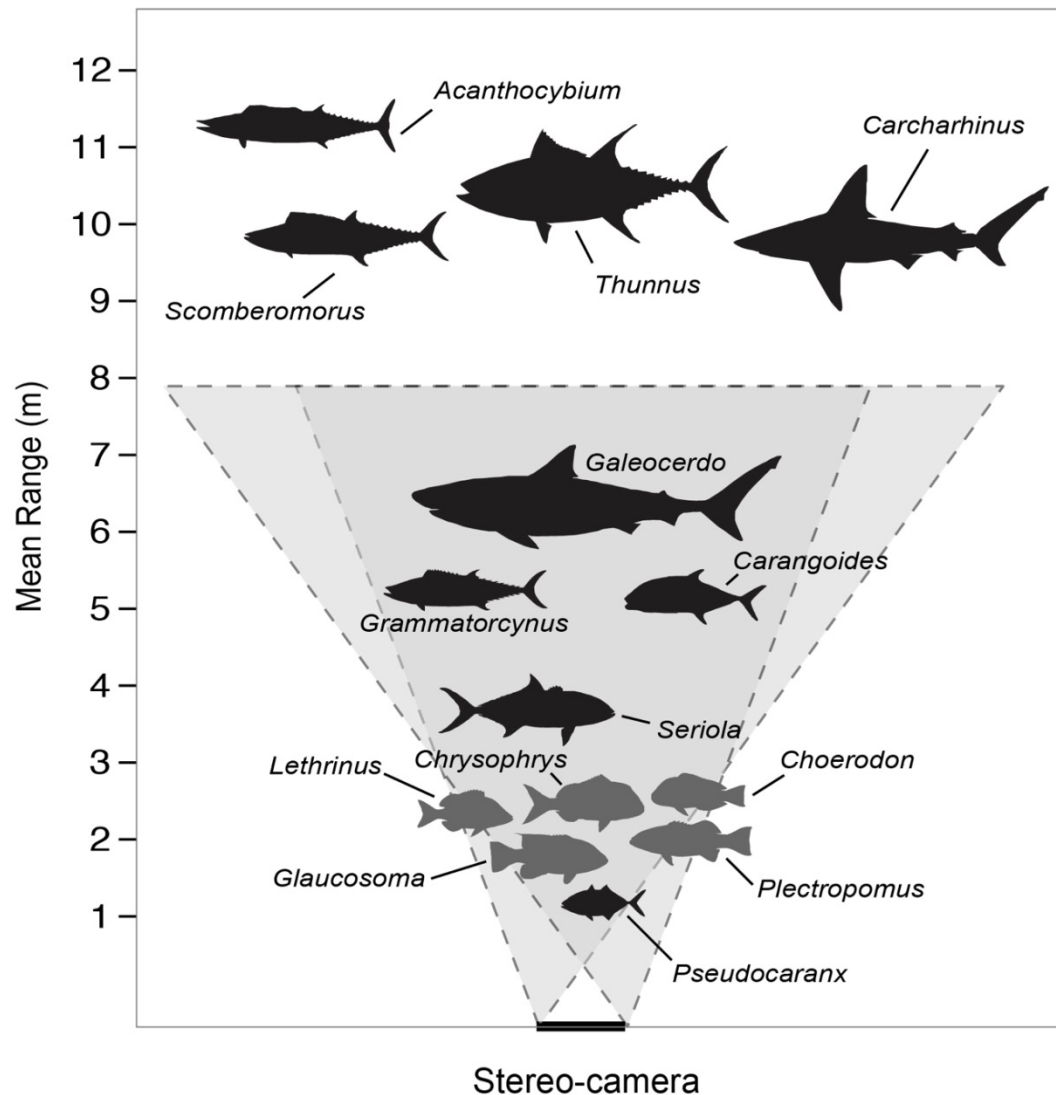
Curtin University is a trademark of Curtin University of Technology  
CRICOS Provider Code 00301J



# PELAGIC STEREO-BRUVS



Santana-Garcon J, Leis JM, Newman SJ, Harvey ES (2013) Presettlement schooling behaviour of a priacanthid, the Purplespotted Bigeye Priacanthus tayenus (Priacanthidae: Teleostei). Environmental Biology of Fishes:1-7



Surface deployed, anchored or controlled

Need to investigate alternate methods of attraction.

Flashing lights, spinning lures, FADs

Can depth be controlled by an AUV?

Increasing field of view

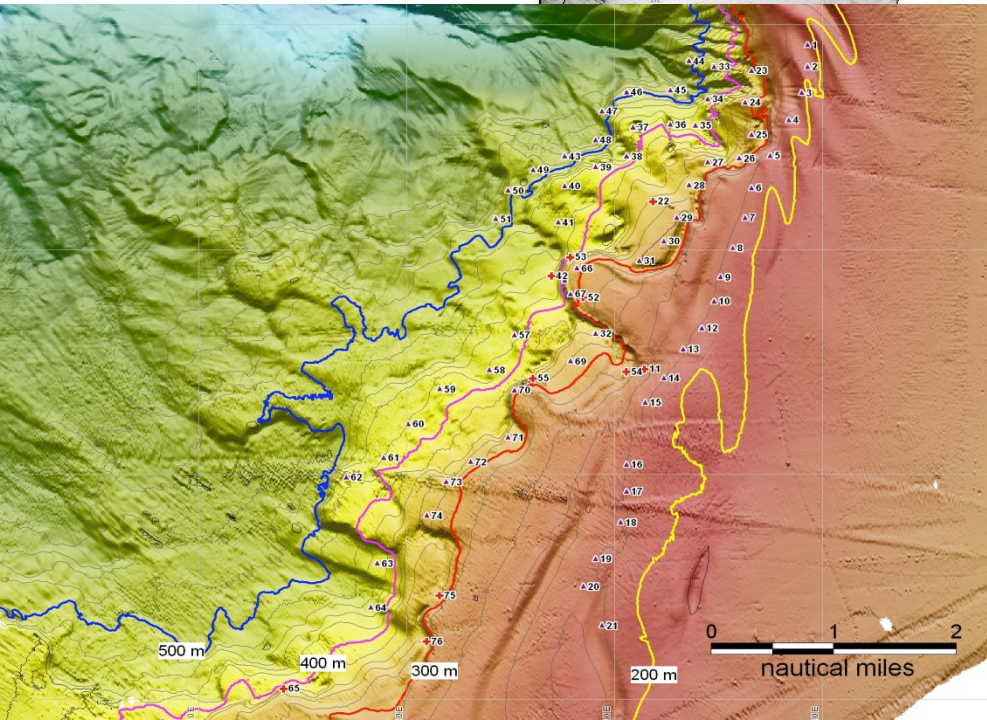
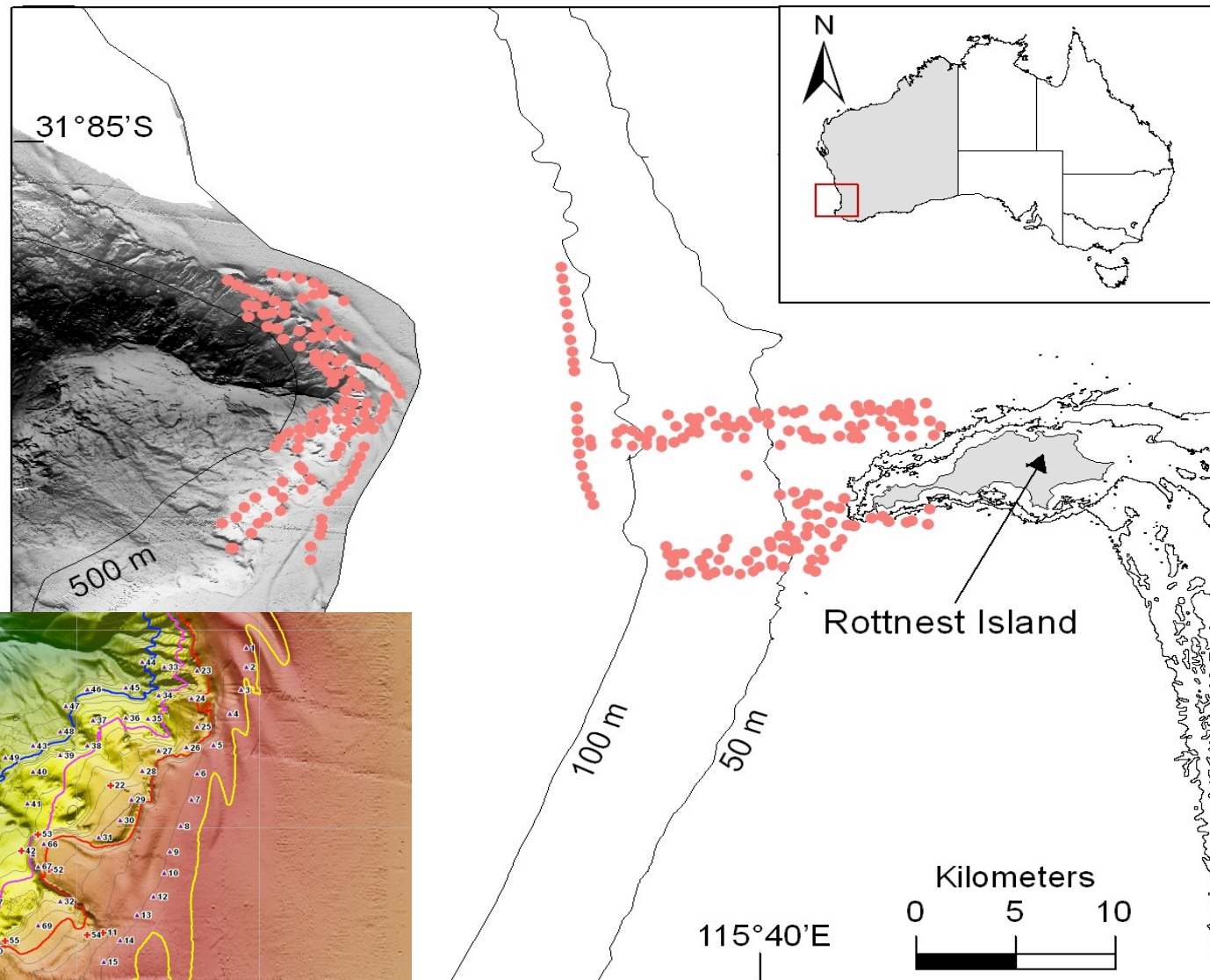
Acoustic cameras?

Laser line scanning systems?

Other technologies?



# Acoustics aid sampling and data analysis



Curtin University



# Unmanned Aerial Vehicles

High resolution still and video

LIDAR

Hyperspectral

# The need for automation



- Time. 1 BRUV 2 ~ 3.5hrs
- Cost = \$180-230 salary for analysis  
5000 hrs annually = \$1 000 000 +
- User adoption: Inhibits uptake

# Is automation realistic?



Motion detection

Tracking

Automated measurement

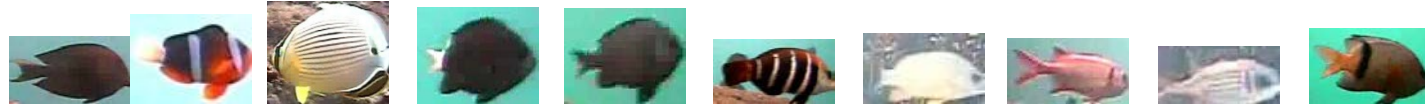
Species Identification











Labeled training data sets, Morphometric information and behavior

ANNs, Support Vector Machines, Classification and decision trees

# Is automation realistic?

MacLeod, Benfield and Culverhouse, Nature 467(9 ): 154-155



	Acanthurus Nigrofusus	Amphiprion Clarkii	Chaetodon Lunulatus	Chromis Margaritifer	Dascyllus Reticulatus	Hemigymnus Fasciatus	Lutjanus Fulvus	Myripristis Berndti	Neoniphon Sammarra	Plectroglyphidodon Dickii
	<b>29</b>			1	2					
		<b>45</b>								
			<b>29</b>							
				<b>17</b>						
					<b>14</b>					
	2	1		2	1	<b>39</b>				2
							<b>5</b>		2	
					1			<b>30</b>		2
									<b>58</b>	
										<b>16</b>



# Automatic Fish Measurement



# Challenges

## Data storage and accessibility

Numbers (MaxN, Density, length range)

Metadata

Imagery, annotated files, calibration files

1 hour stereo-video = 32 GB data

(8000 hours = 256,000 GB)

## Data with public funding

Other users need to have ability to access  
download, reanalyse, verify

# Opportunities due to technological innovation?

Need non destructive and fishery independent data.

Fine scale optical sampling

Can we increase scale and resolution?

Deeper sampling with multiple delivery tools (AUVS, ROVS, Baited cameras/Landers)

Deployed equipment need to be collecting multiple types of data

Investment in automated image analysis